

**Time-Correlation Analysis
of a Class of Nonstationary
Signals with an Application
to Radar Imaging**

Ta-Hsin Li and Jerry D. Gibson

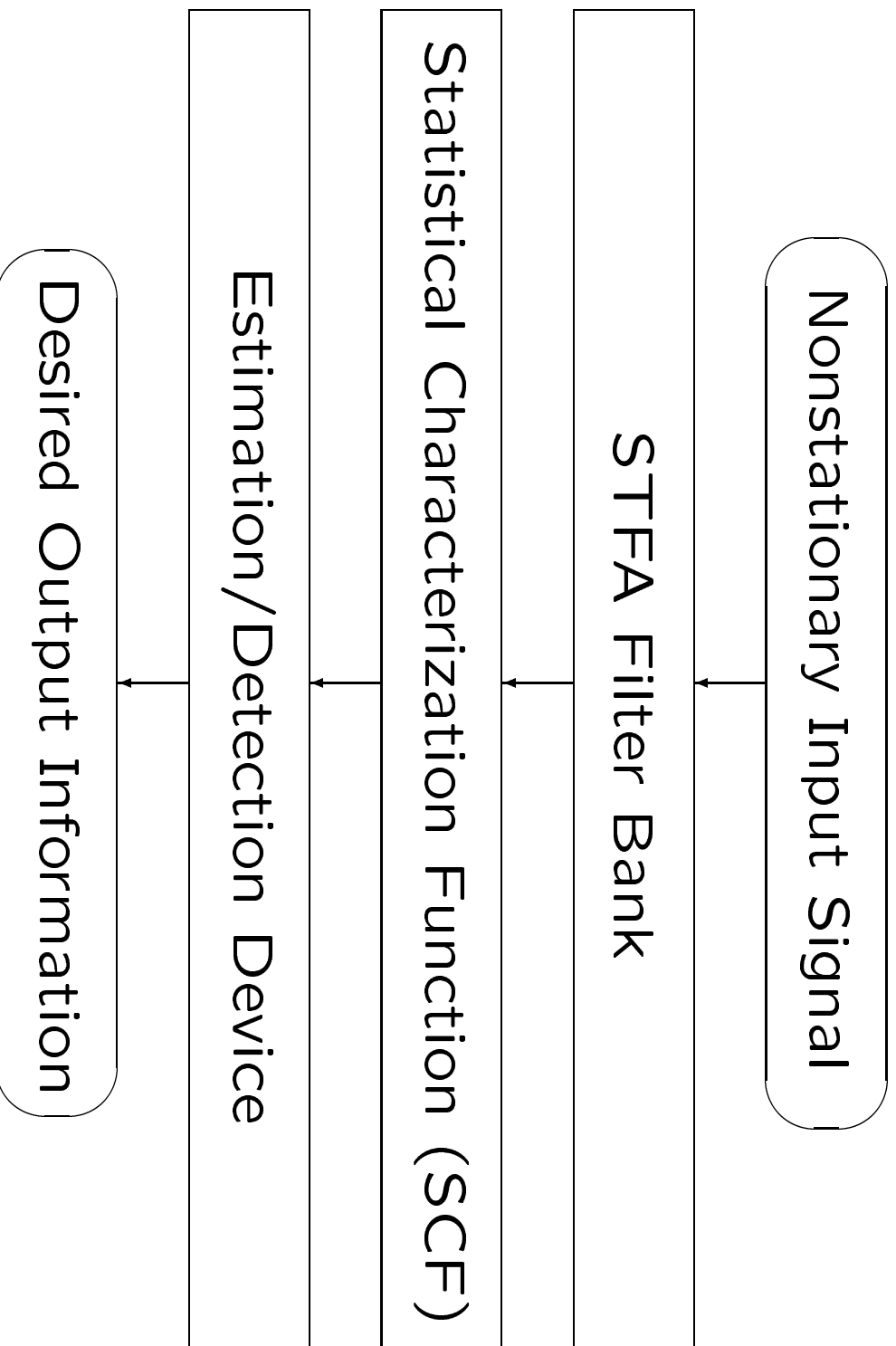
Texas A&M University

College Station, Texas 77843, USA

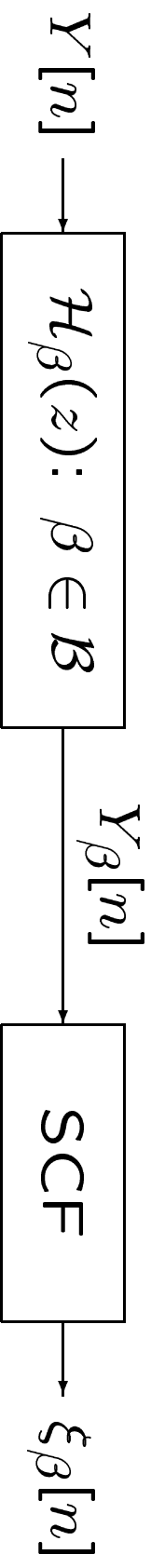
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For presentation at ICASSP'97, April 21–24, 1997, Munich, Germany

STATISTICAL TIME-FREQUENCY ANALYSIS (STFA)



STFA: FILTER BANK AND SCF



Examples of Filter Banks

- Repeated differencing (RD):

$$\mathcal{H}_k(z) = (1 - z^{-1})^k$$

where $k = 0, 1, 2, \dots$

- Complex exponential filtering:

$$\mathcal{H}_\alpha(z) = \frac{1}{1 - \alpha z^{-1}}$$

where $\alpha = \eta e^{j\theta}$, $\eta \in (0, 1)$

Examples of SCFs

- Output variances:

$$\sigma_\beta^2[n] = \text{Var}\{Y_\beta[n]\}$$

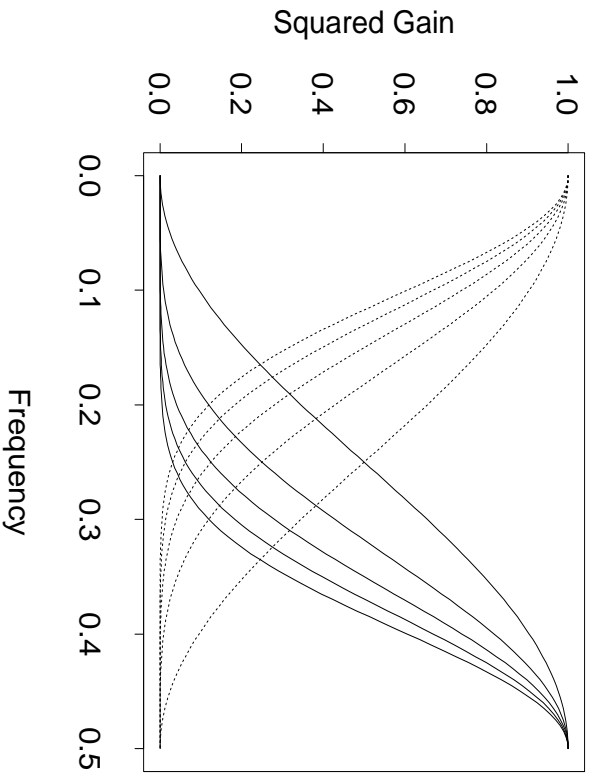
- Output lag-one autocorrelation coefficients:

$$\gamma_\beta[n] = \text{Corr}\{Y_\beta[n], Y_\beta[n - 1]\}$$

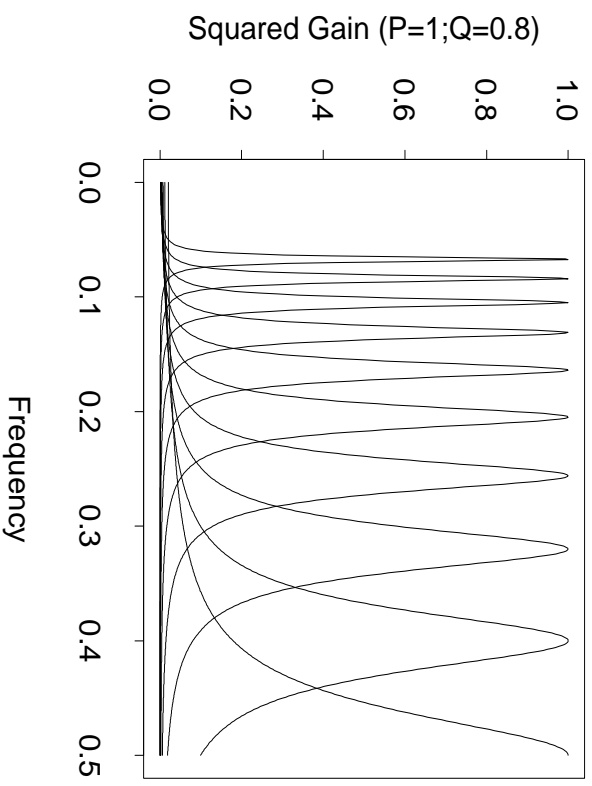
- Output zero-crossing rates:

$$\zeta_\beta[n] = \text{Pr}\{Y_\beta[n] Y_\beta[n - 1] < 0\}$$

Frequency Response of Repeated Summation & Differencing



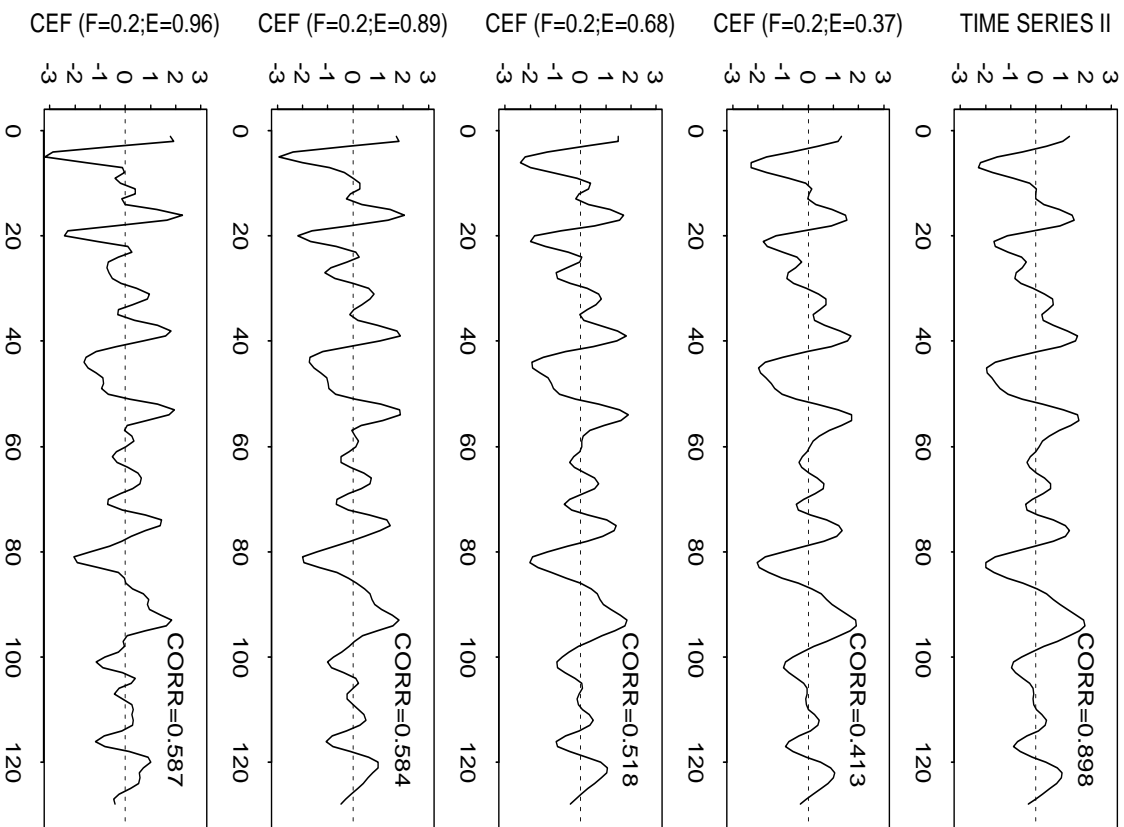
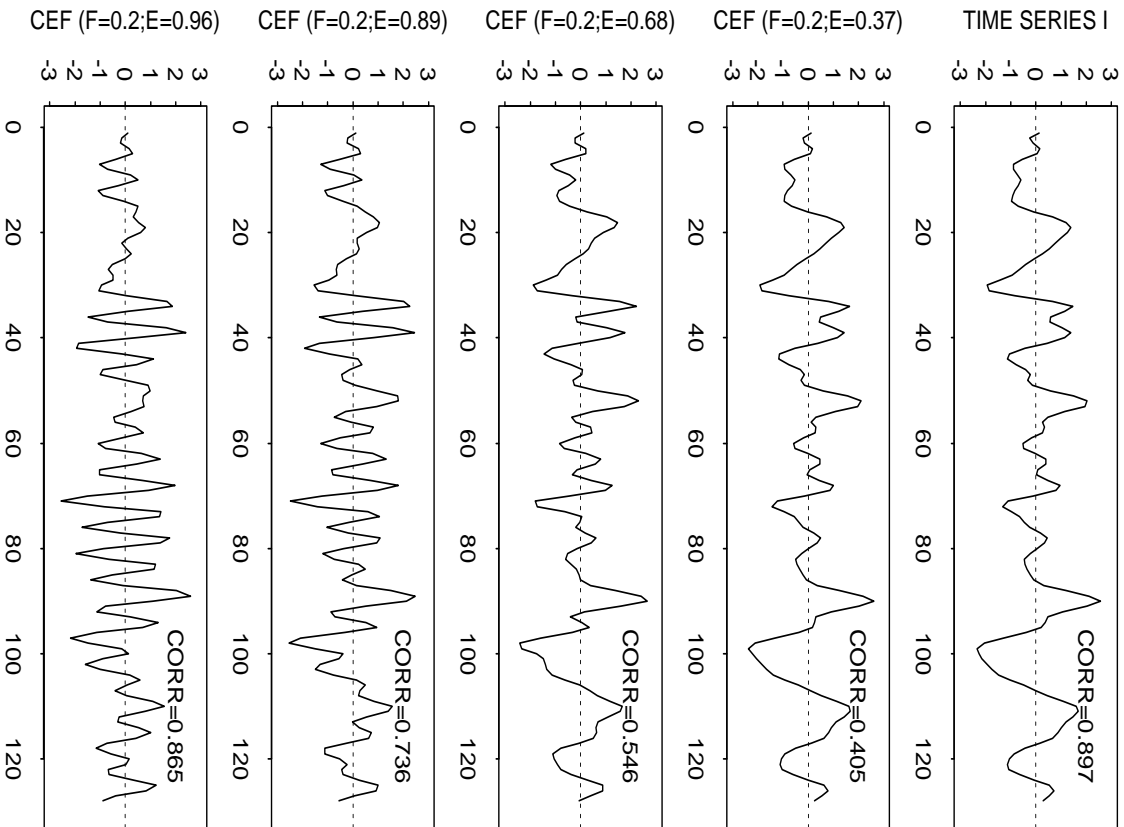
Frequency Response of New CEF
 $\text{ETA} = \text{PSI}(F)$, $F = 0.5 \cdot Q \wedge k$



WHAT DOES AN SCF DO?

- Data Reduction and Compression:
 - Summarize important features of filter output
- Signal Robustification and Enhancement:
 - Reject statistical variations of stochastic signals
 - Reject interference and noise via combination with an STFA filter bank

STFA FILTER BANK AND SCF AT WORK



INTERPRETATIONS OF OUTPUT ZCR'S

- Measure of oscillation patterns
- Measure of spectral mass center
- Equivalence to power spectral density if coupled with a suitable STFA filter bank

A CLASS OF NONSTATIONARY PROCESSES

- Nonstationary model:

$$Y(t) = X(g(t))$$

- Motivations: for returned Doppler signals,

$$g(t) = t - \frac{2}{c} \left(r_0 - \int_0^t v(\tau) d\tau \right)$$

c : velocity of wave propagation

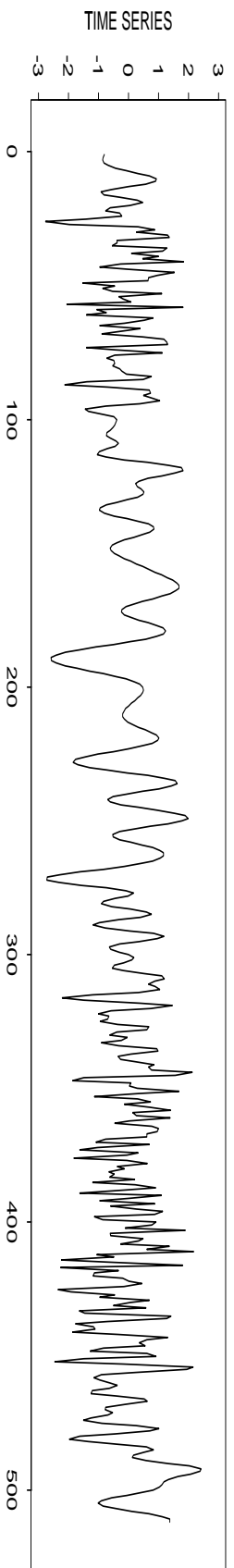
r_0 : initial distance between receiver and target

$v(t)$: instantaneous velocity of target

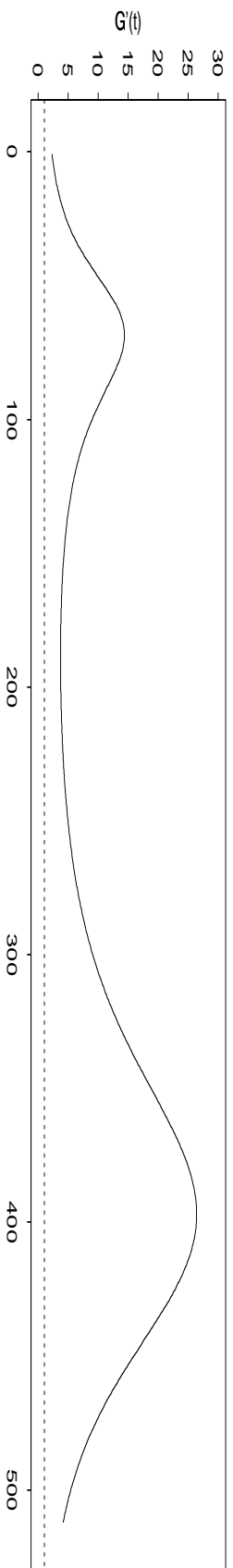
BASIC ASSUMPTIONS

- $X(t)$ is a zero-mean stationary random process
- $g(t)$ is a “smooth” and monotone function which maps the interval $[0, T]$ onto itself
- Call $g(t)$ the distortion function (DF)

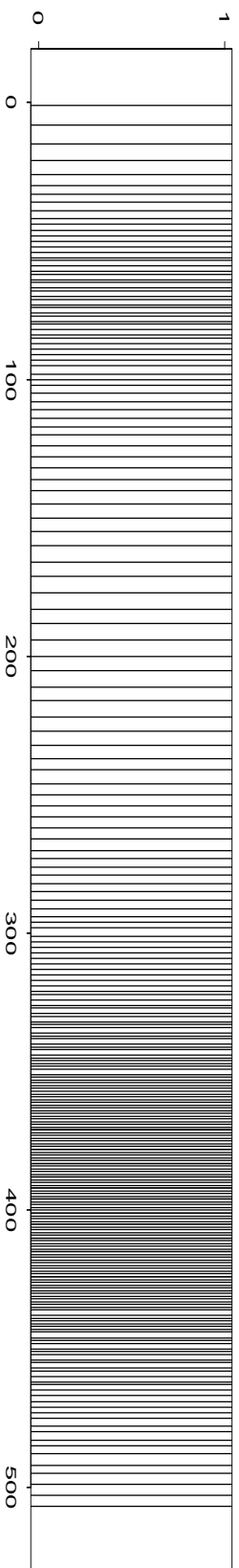
NonStationary Process: $Y(t)$



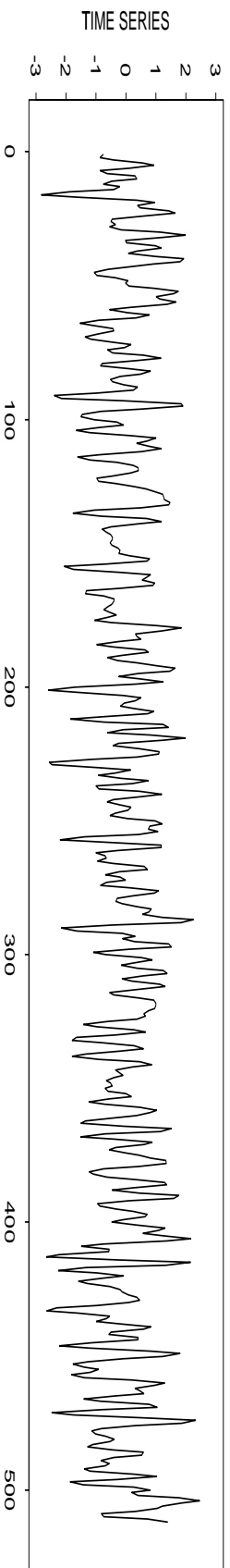
Derivative of Distortion Function



NonUniform Sampling Points for $Y(t)$



Stationary Process: $X(t)$



WHAT DOES A DF DO?

- Instantaneous ZCR inflation factor:

$$\zeta(t) = \dot{q}(t) c_0$$

where c_0 is the ZCR of $X(t)$

- Instantaneous bandwidth inflation factor:

$$\Omega(t) = \dot{q}(t) \Omega_0$$

where Ω_0 is the bandwidth of $X(t)$

HOW TO UNDO THE DISTORTION?

- Distortion function estimation:

$$\hat{g}(t) = T \frac{\int_0^t \hat{\mu}(\tau) d\tau}{\int_0^T \hat{\mu}(\tau) d\tau}$$

where $\hat{\mu}(t)$ is an estimator of $\mu(t) \propto \dot{g}(t)$

- Inverse transformation:

$$\hat{X}(t) = Y \left(\hat{g}^{-1}(t) \right)$$

STATISTICAL TIME-FREQUENCY ANALYSIS

- Choice of filter bank: repeated differencing (RD)
- Choice of SCF: ZCR's from the RD filter bank
- Results of STFA: $\zeta_k(t) = \dot{g}(t) c_k$ ($k = 0, 1$)
 - $\{\zeta_0(t), \zeta_1(t)\}$: ZCR's of $Y(t)$ and $\dot{Y}(t)$
 - $\{c_0, c_1\}$: ZCR's of $X(t)$ and $\dot{X}(t)$

NONPARAMETRIC DF ESTIMATION

- Sampling: $Y[n] = Y(n\Delta)$
- Filtering: $Y_k[n] = \mathcal{H}_k(z) Y[n]$, $(k = 0, 1)$
- Instantaneous SCF:

$$Z_k[n] = \mathcal{I}\{Y_k[n] Y_k[n-1]^* < 0\} \in \{0, 1\}$$

NONPARAMETRIC DF ESTIMATION (CONT'D)

- Regression setting:

$$Z_k[n] = \mu_k(n\Delta) + \epsilon_k[n]$$

where

$$\mu_k(n\Delta) = E\{Z_k[n]\} = g(n\Delta) \epsilon_k \Delta$$

- Nonparametric smoothing:

$$\hat{\mu}_k(n\Delta) = \text{Smooth}\{Z_k[n]\}$$

SIGNAL ENHANCEMENT BY STEA

- SNR in the regression problems:

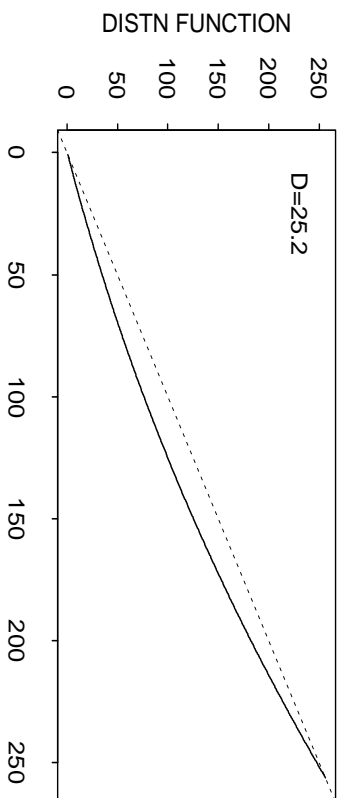
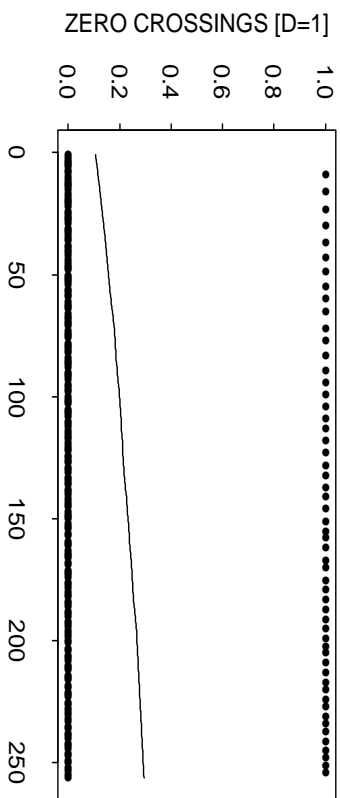
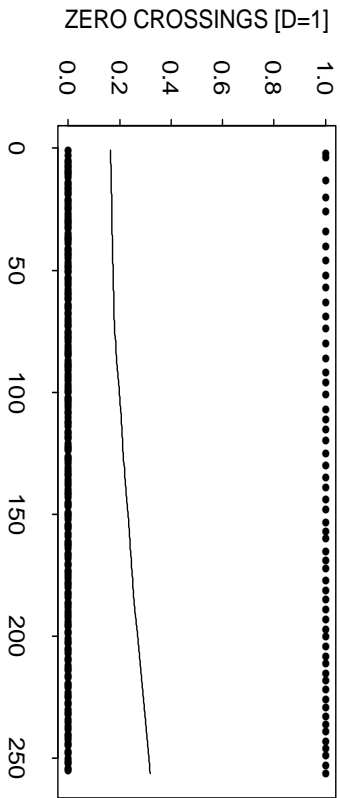
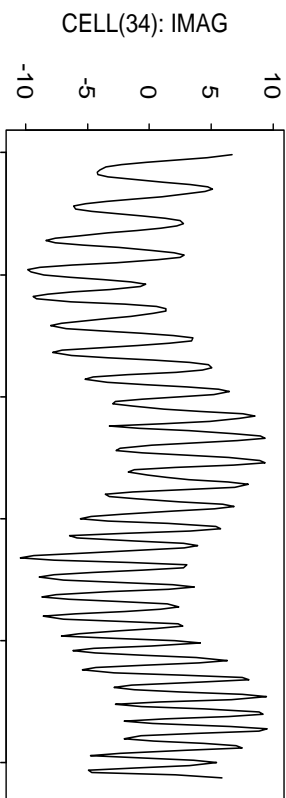
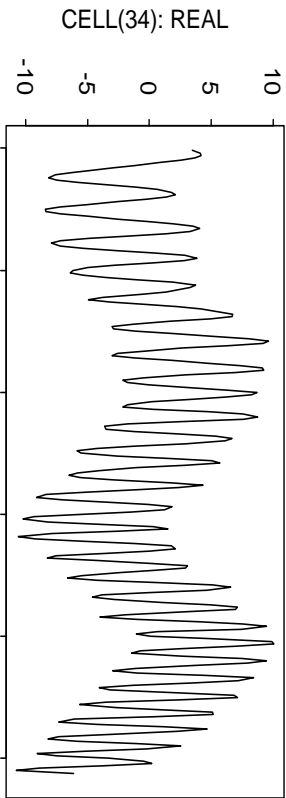
$$\text{SNR}_k(n\Delta) = \frac{(E\{Z_k[n]\})^2}{\text{Var}\{Z_k[n]\}} = \frac{\mu_k(n\Delta)}{1 - \mu_k(n\Delta)}$$

- Implications:

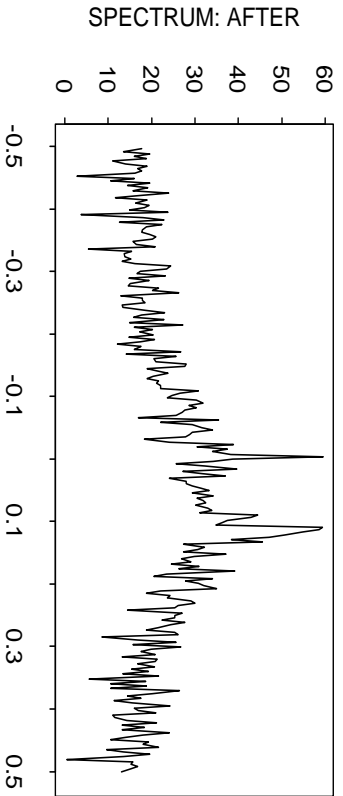
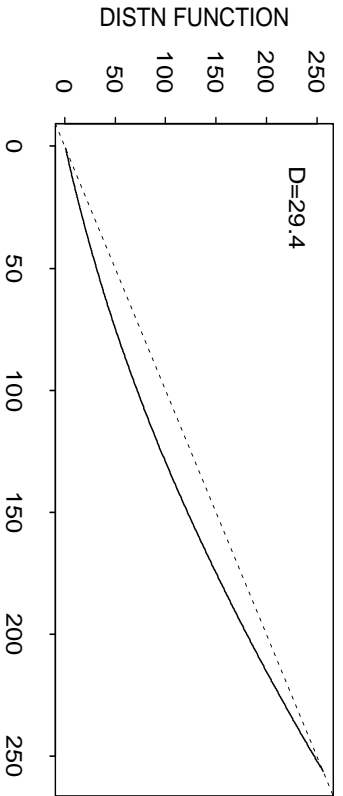
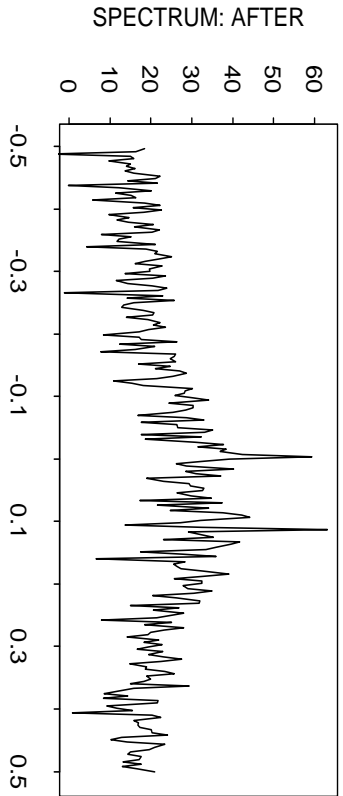
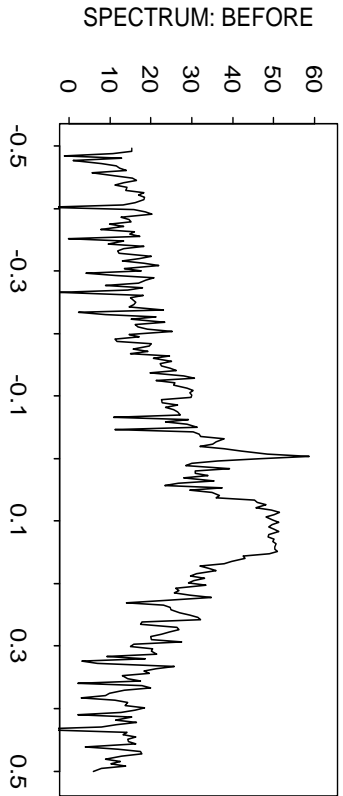
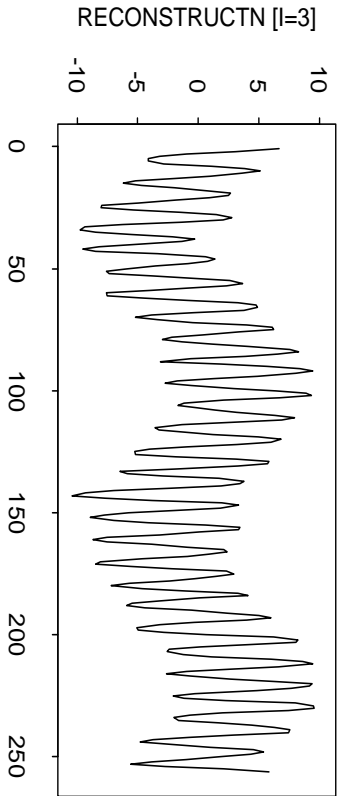
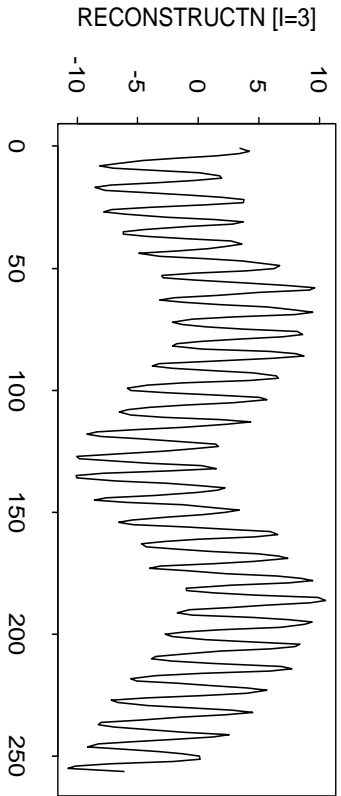
$$\mu(t) \uparrow \iff \text{SNR}(t) \uparrow$$

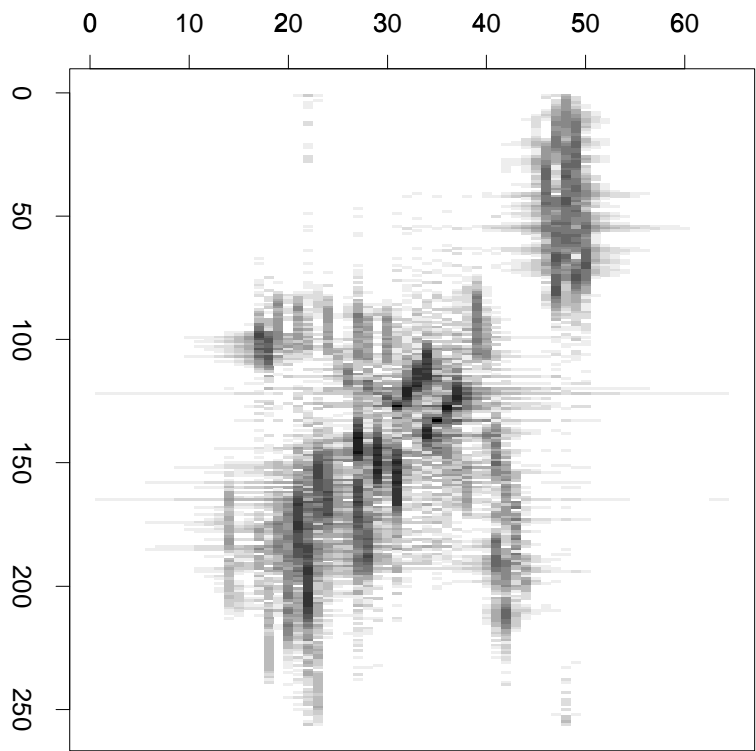
$$\text{SNR}_1(t) > \text{SNR}_0(t) \iff c_1 > c_0$$

EXAMPLE OF DISTORTION CORRECTION

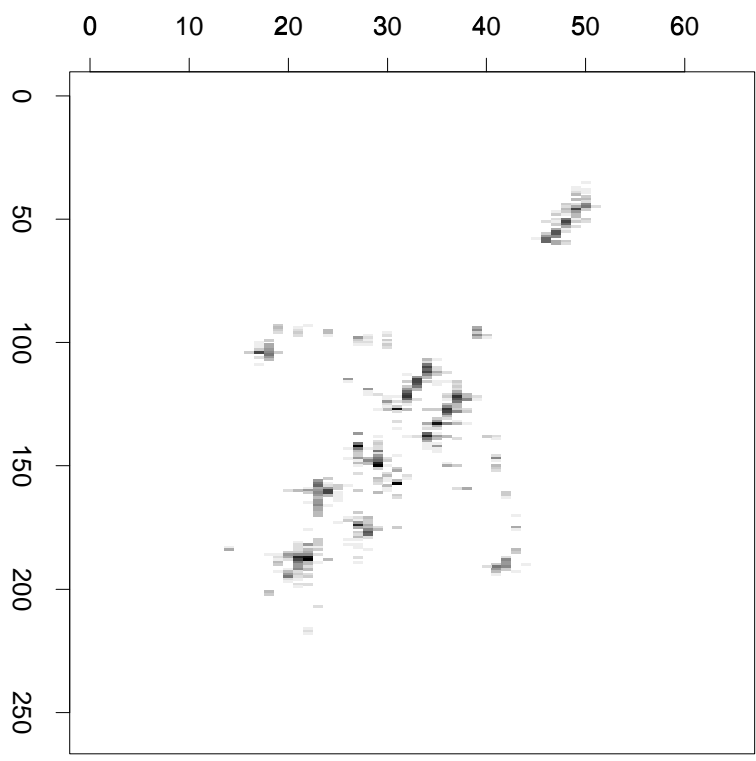


EXAMPLE OF DISTORTION CORRECTION (CONT'D)





ISAR IMAGE OF B727S



ISAR IMAGE OF B727S (DEBLURRED)

CONCLUSIONS

- Statistical time-frequency analysis framework
- Combination of STFPA filter banks with statistical characterization functions (SCF's)
- Data reduction and compression, signal robustification and enhancement